

# Paresh Bhambhani

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## CONTACT INFORMATION

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## RESEARCH INTERESTS

Multi-Agent Robotic Systems, Swarm algorithms, Multi-agent exploration, Single/Multi Robot SLAM, Autonomous Robot Motion, Robot Simulations

## EDUCATION

### Colorado State University

Ph.D. Candidate, Electrical and Computer Engineering

- Research Area: Multi-Agent (Swarm) Robotic systems
- Advisor: Anthony Maciejewski

### Colorado State University

Masters in Electrical and Computer Engineering

- GPA: 3.77

### RCOEM, Nagpur University

B.E. in Electronics Engineering, June 2010

- GPA: 3.7

## GRADUATE COURSEWORK

- |  |   |
|--|---|
| <input type="checkbox"/> Robot Motion Planning | <input type="checkbox"/> Fundamentals of Robot Mechanics and Controls     |
| <input type="checkbox"/> Topics in Robotics    | <input type="checkbox"/> Optimization Methods - Control and Communication |
| <input type="checkbox"/> Machine Learning      | <input type="checkbox"/> Application of Random Processes                  |
| <input type="checkbox"/> Numerical Analysis I  | <input type="checkbox"/> Overview of System Engineering Processes         |
| <input type="checkbox"/> Non-Linear Controls   | <input type="checkbox"/> Computer Organization and Architecture           |
| <input type="checkbox"/> Linear Algebra        | <input type="checkbox"/> Ethical Conduct of Research                      |

## COMPUTING SKILLS

- Languages and Packages: Matlab scripting, Python, C/C++, Latex, V+, ROS, limited exposure to Perl, Version Control (git, github), Bug-Tracking (Bugzilla)
- Algorithms: Experience programming/evaluating/debugging Swarm behavior algorithms and robot motion planning, Robot localization and mapping, Bayesian Filters (KF, EKF, Particle)
- Hardware and Platforms: Adept MV-One Robots, Marvell PXA and Harman Development Platforms, limited exposure to BeagleBone Black and Raspberry Pi
- Operating Systems: Unix/Linux, Windows

## ACADEMIC EXPERIENCE

### Colorado State University

*PhD candidate*

December, 2015 - present

- Current Research focuses on development of multi-agent/swarm system models for collective group tasks such as flocking, obstacle avoidance and collective exploration.
- Use of graph theoretic methods for consensus and group objective achievement.
- Explore indoor environments without using multi-robot SLAM.

*Graduate Teaching Assistant*

July, 2014 - present

- Teaching Assistant with Systems Engineering Dept. for ENGR 501 and Mech 501.
- Grading Student Assignments, projects and presentations.
- Preparing Lecture Slides and Homework.
- Address students' administrative and coursework related questions.

GRADUATE  
PROJECTS

- Creation of Swarm flocking framework based on the works of Olfati et al.
- Creation of *Swarm Chemistry* framework based on the works of Sayama et al.
- Creating Task Level Dynamic controller for Puma 560 robot.
- Pick & Place, and obstacle avoidance program for Adept MV-One robot.
- Creation of C program to generate robot joint values, using inverse kinematics, for Puma 560 robot.
- Debugging and resolving issue of offset in null-space motion of Adept MV-One Robot.
- Comparing the performance of K-Means vs the Particle Swarm Optimization on digits and wine datasets.

PROFESSIONAL  
EXPERIENCE

**Marvell Semiconductors**, Pune, India

*SQA and Automation Engineer*

September, 2010 - December, 2013

- Qualified Marvell's Bluetooth-Wifi solution releases for a customer tablet on WHCK.
- Developed perl scripts for automation of protocol testing scenarios.
- Carried out Customer requirement analysis, development of test environment and test setup, and creation of test scenarios.
- Developed test plans and test cases for testing and validation of Bluetooth and Wifi protocols.
- Led a team of 5 people to carry out testing of Bluetooth and Wifi functionality for 4 customer projects.
- Independently worked on creating complete testing strategy, from requirement analysis to test setup and script creation, of HCI Audio architecture for BlueZ bluetooth stack on Linux.
- Co-created SQA-Bluetooth team's intranet website for Test-bed reservation.

LEADERSHIP  
EXPERIENCE

- 'Team Lead' at Marvell Semiconductors for 4 projects leading a team of 5 members.
- Student President in 2010 and Student vice-president in 2009 of Electrolitz, Electronics Department student society, RCOEM Nagpur.
- Cofounder of Entrix, a Co-curricular and Academic program for students to provide them with technical education beyond classroom which is now in its 9<sup>th</sup> year at RCOEM, Nagpur.
- Captain of Electronics Department debate team at RCOEM, Nagpur.

HONORS AND  
AWARDS

- Received Marvell's recognition award for resolving critical pre-launch product issues at client site at Suwon, South Korea.
- First Place in "Best English Article" in Aarohi-09, a national level competition at VNIT, Nagpur, India.
- Second place in "Reacto Drive" in Quark-08, a National level Competition at BITS, Goa, India.
- Awarded academic excellence certificate for the year 2007-2008.